Garbage Collection for Temporal Stream Algebra (TSA) and Event-Mill

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Introduction
Complex Event Queries

Complex event queries are standing queries that are continuously evaluated against a stream of input events and thereby produce complex output events.

Events

Events = tuples in potentially infinite data streams with finite prefix at each point in time.

Problem

New tuples are continuously buffered at least temporarily. If the buffered tuples are not removed after some time, memory runs full.
The Way to Garbage Collection

We have:

- query with input and output streams.
- progress of the output stream = the upper bound\(^1\)
- available part of the output stream = the part up to the upper bound.

\(^1\)Simon Brodt, Francois Bry. Analysing Temporal Relations.
The Way to Garbage Collection

Goal 1

Determining those tuples in the input streams of a query that cannot contribute to further output tuples.
Goal 2

Determining that part of an input stream which contains the irrelevant tuples → selection conditions.
Goal 3

Determining lower bounds of the relevant part of an input stream \( \rightarrow \) values for selection conditions.
Running Example
Running Example - Airport Use-Case

If there is a smoke warning in an area and the responsible warden does not give a report within 5 minutes, then an alarm is raised.

```
DETECT
  Alarm {area {var X}}
ON
  event s: Smoke {area {var X}}
  not event r: Report {area {var X}}
WHERE
  s.rt.end <= r.rt.begin,
  r.rt.begin <= s.rt.end + 5 min
END
```

*rt.begin* is the beginning, *rt.end* is the end of the reception time interval (commonly known as "system time") of an event.
Determining Upper Bounds

Before the 1st step of the naïve evaluation.

![Diagram showing time intervals for Alarm, Report, and Smoke]
Determining Upper Bounds

1st step of the naïve evaluation after 12 minutes.

No report following a smoke warning within 5 minutes $\Rightarrow$ create an alarm.
let $r_4$ be a new report after 13 minutes.
Determining Upper Bounds

2nd step of the naïve evaluation at \( rt = 14 \).

\[ \Rightarrow a_4 \text{ is raised too rashly at time } t = 12 \text{ min.} \]
Determining Upper Bounds

1st step of the naïve evaluation at $rt = 12$.

$⇒$ Upper bound of $Alarm = Upper bound of Report - 5\text{ Min.}$
Determining Upper Bounds

1st step of the incremental evaluation at $rt = 12$ (correct).

Incremental evaluation determines the upper bound of the output stream based on the upper bounds of the input streams.
Determining Lower Bounds

Reception time of the alarm = reception time of the original smoke warning.

Relevance analysis: Lower bounds of the future part of the output stream determine lower bounds to the relevant part of the input streams.
Determining Lower Bounds

A report is only relevant to a smoke warning if it occurs after the warning.

Relevance analysis: Lower bounds of the future part of the output stream determine lower bounds to the relevant part of the input streams.
Relevance Analysis for the Running Example
Algorithm

Goal (at each step of the incremental evaluation)

- Determine the lower bounds for input streams.
- Determine the relevant/irrelevant tuples.
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- Determine the lower bounds for input streams.
- Determine the relevant/irrelevant tuples.

Building blocks
1. Keep values with respect to a query/a program (lower bounds).
2. Keep functions (compute keep values for input streams from progress of output stream).
3. Relevance condition (selection condition for relevant tuples based on keep values).
4. Relevance formula (parameterized version of the relevance condition).
Algorithm

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Output: relevance conditions
Only tuples with attribute values greater than the keep values, can contribute to further output tuples.
Relevance Formula

- parametrized version of the relevance condition.
- defined with respect to the timestamp attributes of a temporal stream.

Relevance Formula for Smoke

\[ rt.end > Smoke:rt.end, \]

where \( Smoke:rt.end \) is the parameter for a keep value.
Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

Temporal conditions

$\text{Alarm: } rt.end < a.rt.end$ - holds for new output tuples
Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

**Temporal conditions**

$\text{Alarm: } rt\text{.end }< a\text{.rt\_end}$
$a\text{.rt\_end }= s\text{.rt\_end}$
$s\text{.rt\_end }\leq r\text{.rt\_begin}$

- query specification
Keep Functions

- upper bound of an output → lower bound of an input.
- based on the temporal conditions between the attributes

Temporal conditions

\[\text{Alarm:} \ rt.\text{end} < a.\text{rt}.\text{end} \]
\[a.\text{rt}.\text{end} = s.\text{rt}.\text{end} \]
\[s.\text{rt}.\text{end} \leq r.\text{rt}.\text{begin} \]
\[r.\text{rt}.\text{begin} \leq r.\text{rt}.\text{end} - \text{stream specification}\]
Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

**Temporal conditions**

$\text{Alarm}: \text{rt.end} < a.\text{rt.end}$

$\begin{align*}
a.\text{rt.end} &= s.\text{rt.end} \\
s.\text{rt.end} &\leq r.\text{rt.begin} \\
r.\text{rt.begin} &\leq r.\text{rt.end}
\end{align*}$

$\Rightarrow a.\text{rt.end} \leq r.\text{rt.begin}$
Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

Temporal conditions

$\text{Alarm: } rt.\text{end} < a.\text{rt.end}$

$a.\text{rt.end} = s.\text{rt.end}$

$s.\text{rt.end} \leq r.\text{rt.begin}$

$\Rightarrow a.\text{rt.end} \leq r.\text{rt.begin}$

$s.\text{rt.end} \leq r.\text{rt.end}$

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Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

Temporal conditions

\[
\begin{align*}
\text{Alarm: } rt.end &< a.rt.end \\
\{ a.rt.end & = s.rt.end \text{ or } s.rt.end \leq r.rt.begin \} &\quad \Rightarrow a.rt.end \leq r.rt.begin \quad \Rightarrow a.rt.end \leq r.rt.end \\
r.rt.begin &\leq r.rt.end
\end{align*}
\]

\[
\Rightarrow \begin{cases} 
\text{Alarm: } rt.end < s.rt.end \\
\text{Alarm: } rt.end < r.rt.end 
\end{cases}
\]
Keep Functions

- upper bound of an output $\rightarrow$ lower bound of an input.
- based on the temporal conditions between the attributes

Temporal conditions

\[
\begin{align*}
\text{Alarm: } & rt.end < a.rt.end \\
& a.rt.end = s.rt.end \\
& s.rt.end \leq r.rt.begin \\
& r.rt.begin \leq r.rt.end \\
\end{align*}
\]

\[
\Rightarrow \begin{cases}
\text{Alarm: } rt.end < s.rt.end \\
\text{Alarm: } rt.end < r.rt.end \\
\end{cases}
\]

\[
f_{\text{Smoke: } rt.end} = f_{\text{Report: } rt.end} = \text{Alarm: } rt.end
\]
Keep Values. Beginning of the 2nd Incremental Evaluation

- $f_{\text{Smoke}:rt\text{-}end} = f_{\text{Report}:rt\text{-}end} = \text{Alarm}:rt\text{-}end$
- $\text{Alarm}:rt\text{-}end = 7 \text{ min}$

Diagram:
- Future part
- Relevant part
- Timeline
- Smoke
- Report
- Alarm
- $a_3$
- $r_1$
- $r_2$
- $r_4$
- $s_1$
- $s_2$
- $s_3$
- $s_4$
- $e_1$
- $s_2$
- $rt \text{ [min]}$
Relevance with Respect to a Program

Relevant tuples for a program
Tuples that are relevant for at least one query in the program.

\[ p_1 > v_{b_1} \land p_2 > v_{b_2} \]

\[ p_1 > v_{b_1} \land p_2 > v_{b_2} \]
First approach: Disjunction of the relevance conditions

$$(p_1 > v_{b_1}^{q_1} \land p_2 > v_{b_2}^{q_1}) \lor (p_1 > v_{b_1}^{q_2} \land p_2 > v_{b_2}^{q_2})$$

...precisely, but time-consuming.
Second approach: Keep values with respect to a program

\[(p_1 > v_{q1}^{b_1} \land p_2 > v_{q1}^{b_1}) \lor (p_1 > v_{q2}^{b_1} \land p_2 > v_{q2}^{b_1}) \Rightarrow p_1 > \min\{v_{q1}^{b_1}, v_{q2}^{b_1}\} \land p_2 > \min\{v_{q1}^{b_1}, v_{q2}^{b_1}\}\]

with irrelevant tuples, but non time-consuming (our recommendation)
GC has to delete the tuples that are irrelevant for the program, i.e. for all queries ⇒ negation of the relevance conditions with respect to the program:

\[ p_1 \leq \min\{v_{q_1}^{b_1}, v_{q_2}^{b_1}\} \lor p_2 \leq \min\{v_{q_1}^{b_2}, v_{q_2}^{b_2}\} \]
Query Optimization

After execution of garbage collection

- gray areas - relevant tuples for the queries
- white areas - relevant tuples for the program, but not for the queries

$p_1 \succ v_{b_1}^{q_1} \land p_2 \succ v_{b_2}^{q_1}$

$p_1 \succ v_{b_1}^{q_2} \land p_2 \succ v_{b_2}^{q_2}$
Definitions
Temporal Stream Algebra (TSA), Informal

TSA Operators

- Standard operators of Relational Algebra: Cross product $\times$, Selection $\sigma$, Set Difference $\setminus$ etc.
- Feature: propagation of temporal relations in the stream schema.
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**TSA Operators**
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**Temporal Relation Formulas - TRFs**
- TRFs describe temporal relations between schema attributes.
- $\bot, \top, t_1 op t_2, G_1 \land G_2, G_1 \lor G_2, \neg G$ are TRFs.
- $t, t + c, \min\{t_1, \ldots, t_n\}, \max\{t_1, \ldots, t_n\}$ are temporal terms.
Temporal Stream Algebra (TSA), Informal

**TSA Operators**
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**Stream bound formulas - SBFs**
- SBFs contain the information about attributes, which can be used to obtain a finite prefix of the temporal stream.
- \( \top, \text{bounded}(v, b), H_1 \land H_2, H_1 \lor H_2 \) are SBFs, where \( v \in \text{ATTR} \cup \text{VAR}, b \in \text{BOUND} \) is a stream bound identifier.
Relevance Formula

Example
Let $H = \text{bounded}(p_1, b_1) \lor \ldots \lor \text{bounded}(p_n, b_n)$. The relevance formula for $H$ is $\nabla H = p_1 > b_1 \land \ldots \land p_n > b_n$.

Definition
Let $H$ be a SBF. The relevance formula $\nabla H \equiv \neg \Delta H$ to $H$ is:

- $\nabla \top = \bot$
- $\nabla \text{bounded}(p, b) = p > b$
- $\nabla (H_1 \land \ldots \land H_k) = \nabla H_1 \lor \ldots \lor \nabla H_k$
- $\nabla (H_1 \lor \ldots \lor H_k) = \nabla H_1 \land \ldots \land \nabla H_k$

where $p \in \text{ATTR} \cup \text{VAR}$ and $b \in \text{BOUND}$.
The *keep function* for the stream bound identifier $b_E$ and the input $D_{q,j}$ on position $j$ of the TSA query $q = (D, E)$ is:

$$
fb_{E,q,j} = f_{\H D, G_E, v}
$$

$$
f_{\H D, G_E, v} = \min_{C_E \in dnf(G_E)} \{ f_{\H D, C_E, v} \}
$$

$$
f_{(\H D_1 \land \ldots \land \H D_k), C_E, v} = \min(f_{\H D_1, C_E, v}, \ldots, f_{\H D_k, C_E, v})
$$

$$
f_{(p > b_D), C_E, v} = \begin{cases} 
\infty & \text{if } \text{dist}_{C_E}(v, p) = -\infty \\
-\infty & \text{if } \text{dist}_{C_E}(v, p) = +\infty \\
b_D - \text{dist}_{C_E}(v, p) & \text{else}
\end{cases}
$$

where $\text{bounded}(v, b_E)$ occurs in $H_E$. 


Conclusion

Relevance analysis for complex event queries specified in TSA

- Based on in-depth analysis of temporal relations at compile-time (in contrast to user-defined time-windows or consumption policies)
- Keep functions and relevance formulas determined at compile-time
- Keep values and relevance conditions efficiently determined at runtime

Improvements

- Garbage collection preventing memory leaks
- Optimization of incremental evaluation by minimizing the number of irrelevant tuples taking part in the evaluation

Future work

- Performance evaluation of the approach based on a benchmark
- Relevance and garbage collection for TSA queries beyond temporal relations